

# CHARACTERIZING UNCERTAINTY

LESSON 6

# Linear model assumptions

The linear model rests on some important assumptions:

- Errors are additive and normally distributed
- Errors are homoskedastic (don't vary across  $X$ s)
- Observations are independent (conditional on the linear predictor)
- Linear (in covariates) mean function
- All error/randomness is in the value of the response (i.e., the  $X$  values are precisely known)
- There is no (systematic) missing data

Ecological data rarely conform to these assumptions!



# SYNOPSIS

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*This section dives into the Bayesian methods for characterizing and partitioning sources of error that take us far beyond the classic assumption of a constant Normal variance.*

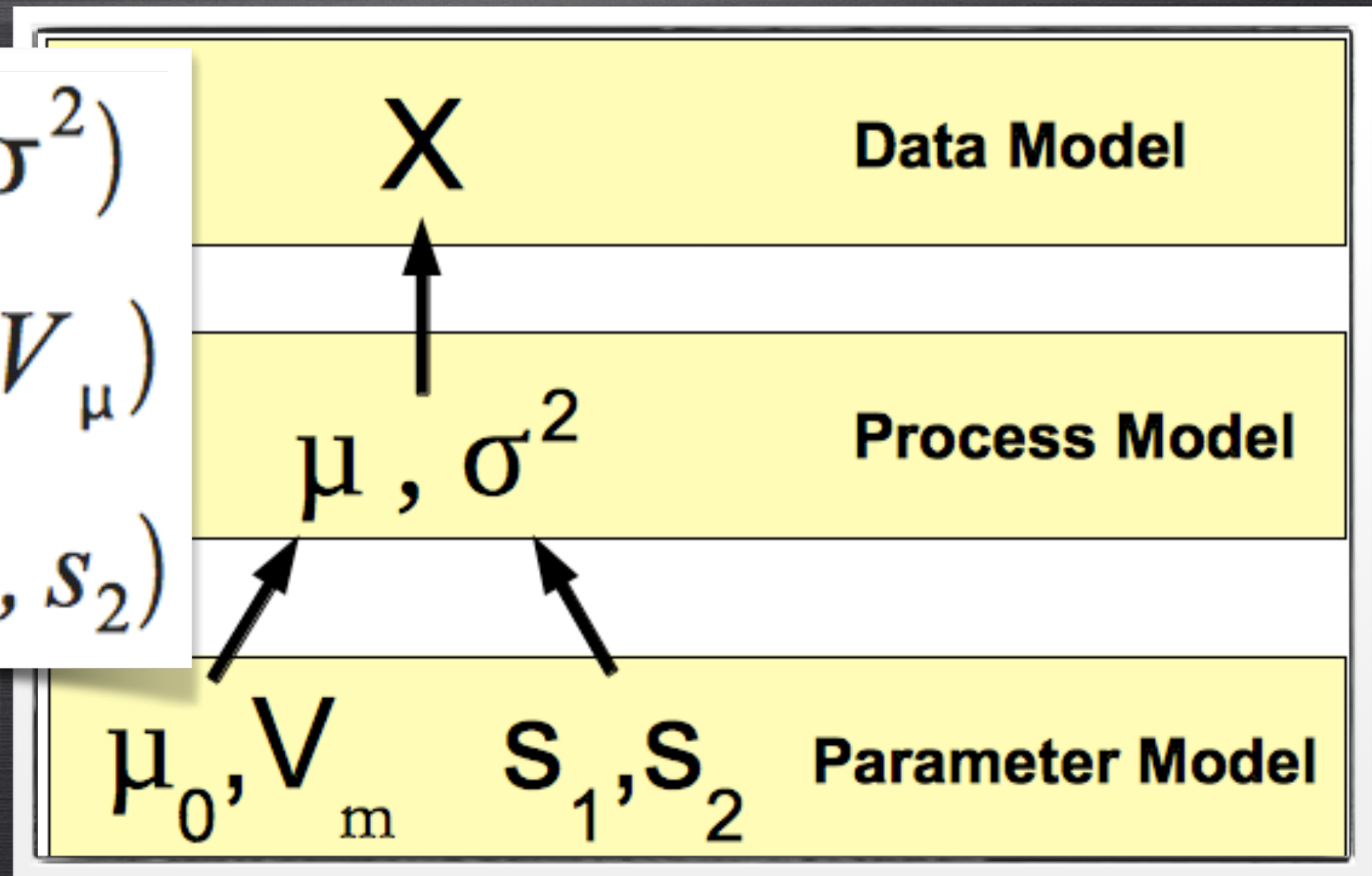
- Non-Gaussian
- Errors in X — Latent variables
- Missing Data
- Hierarchical models
- State-Space (Wed)
- Heteroskedasticity



$$X \sim N(\mu, \sigma^2)$$

$$\mu \sim N(\mu_0, V_\mu)$$

$$\sigma^2 \sim IG(s_1, s_2)$$



# GRAPH NOTATION

$$\vec{y} \sim N(\mathbf{X} \vec{\beta}, \sigma^2)$$

$X \longrightarrow Y$

**Data Model**

$\beta, \sigma^2$

**Process Model**

$B_0, V_b$

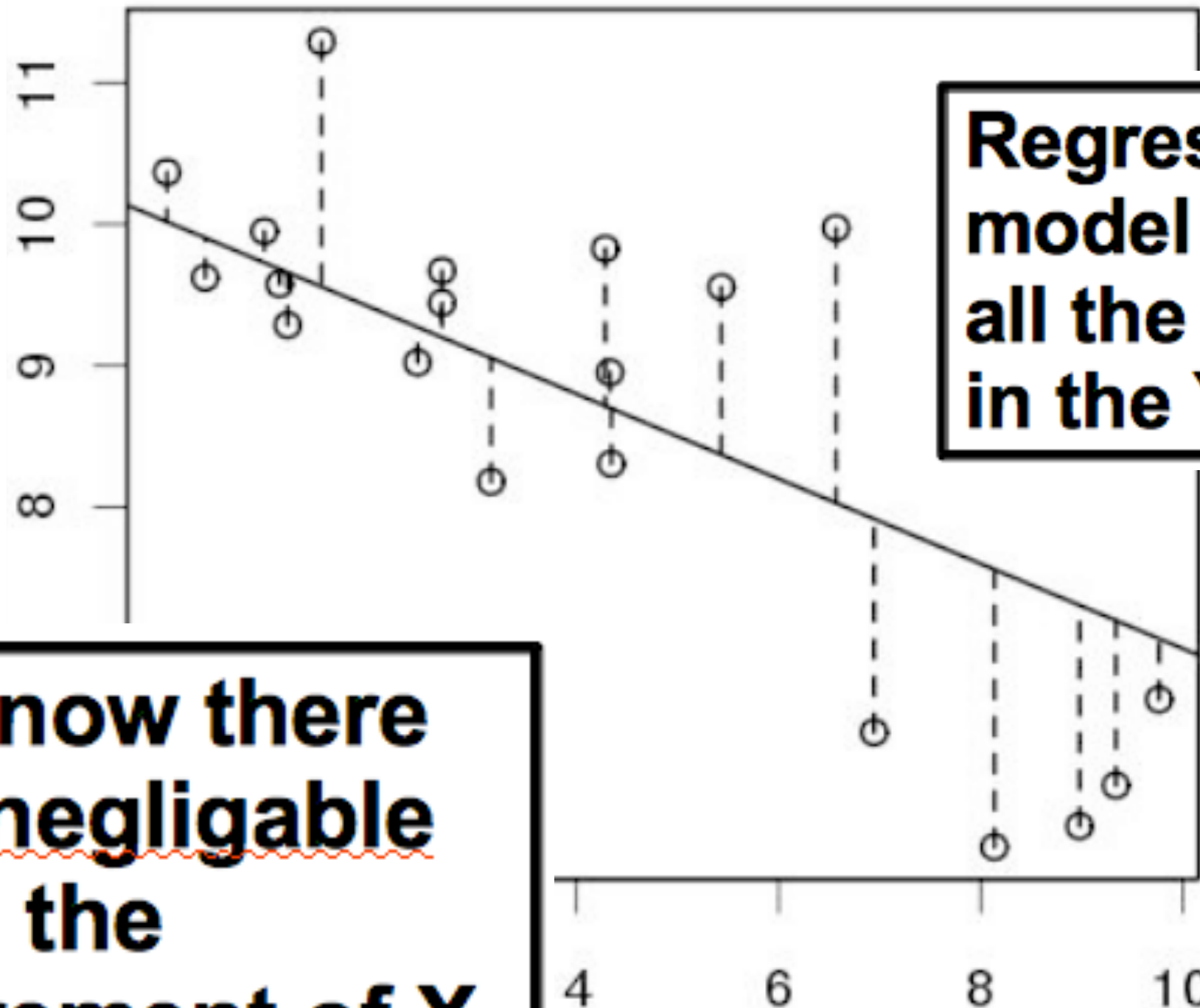
$S_1, S_2$

**Parameter Model**

# LINEAR REGRESSION



# ERRORS IN VARIABLES

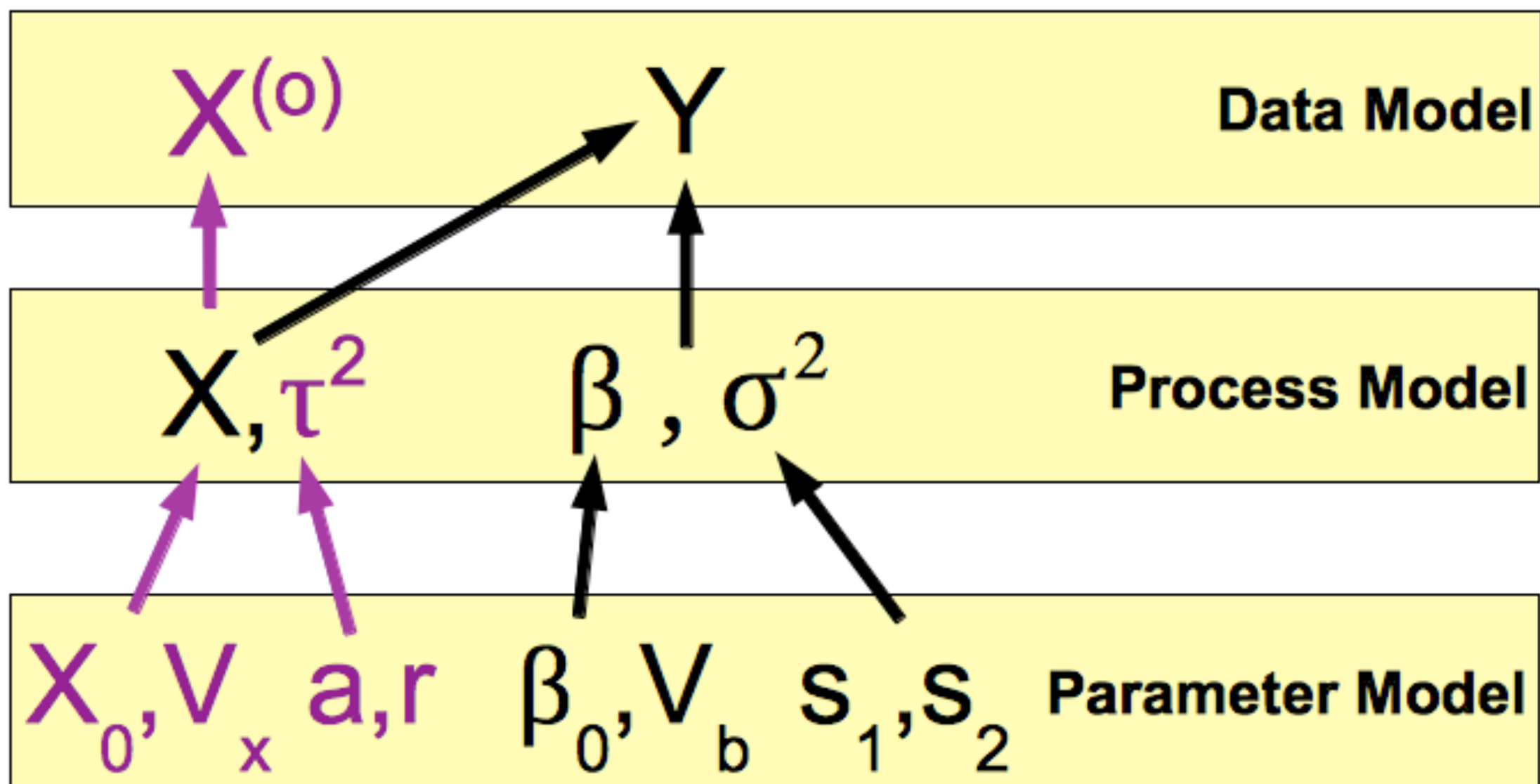


**Regression model assumes all the error is in the Y**

**Often know there is non-negligible error in the measurement of X**

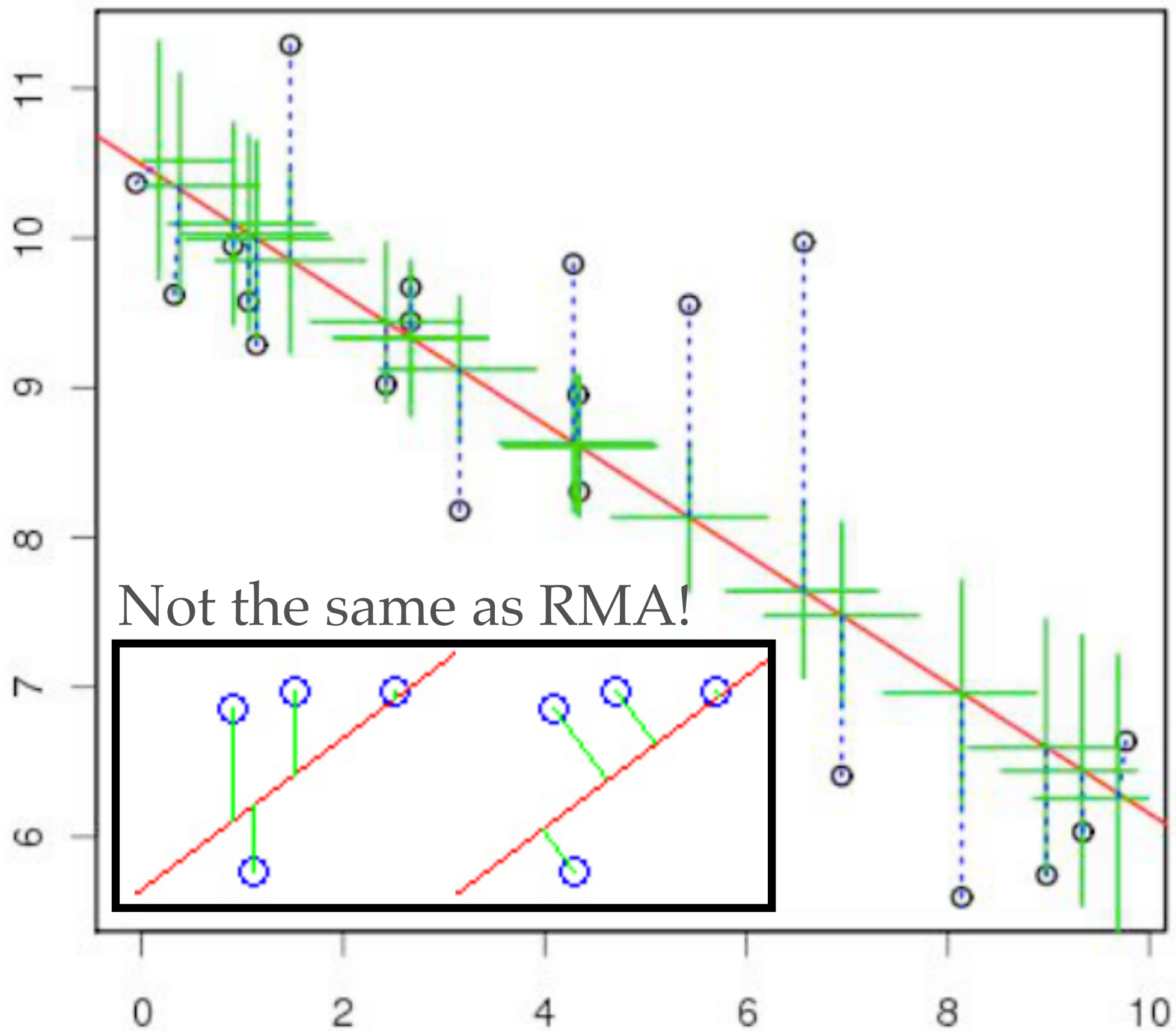
$$\vec{y} \sim N(\mathbf{X}\vec{\beta}, \sigma^2)$$

$$x^{(o)} \sim N(x, \tau^2)$$



```
model {  
  ## priors  
  for(i in 1:2) { beta[i] ~ dnorm(0,0.001)}  
  sigma ~ dgamma(0.1,0.1)  
  tau ~ dgamma(0.1,0.1)  
  for(i in 1:n) { x[i] ~ dunif(0,10)}  
  
  for(i in 1:n){  
    xo[i] ~ dnorm(x[i],tau)  
    mu[i] <- beta[1]+beta[2]*x[i]  
    y[i] ~ dnorm(mu[i],sigma)  
  }  
}
```





Not the same as RMA!

# Additional Thoughts on EIV

$$x^{(o)} \sim g(x|\theta)$$

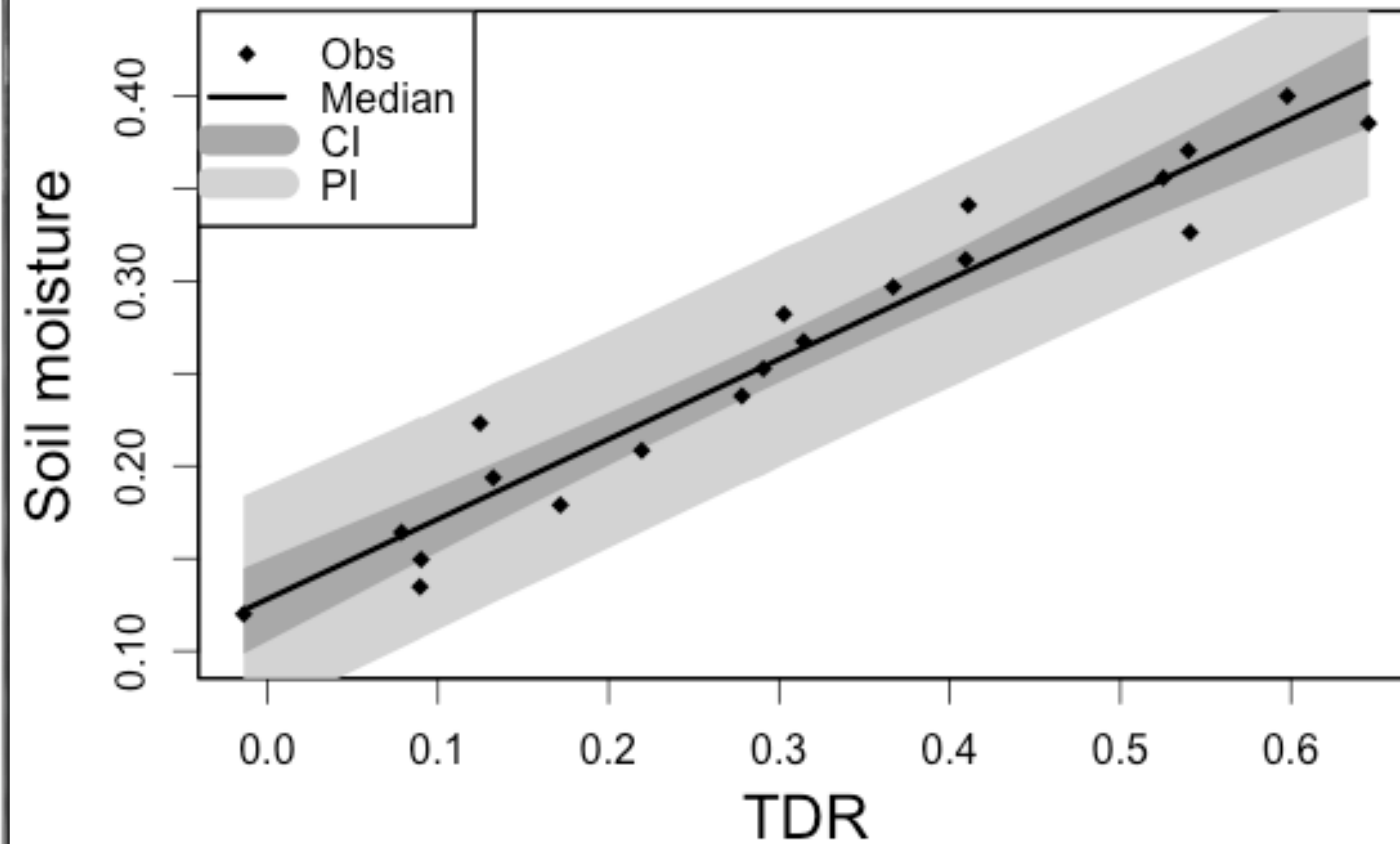
- Errors in  $X$ 's need not be Normal
- Errors need not be additive
- Can account for known biases

$$x^{(o)} \sim N(\alpha_0 + \alpha_1 x, \tau^2)$$

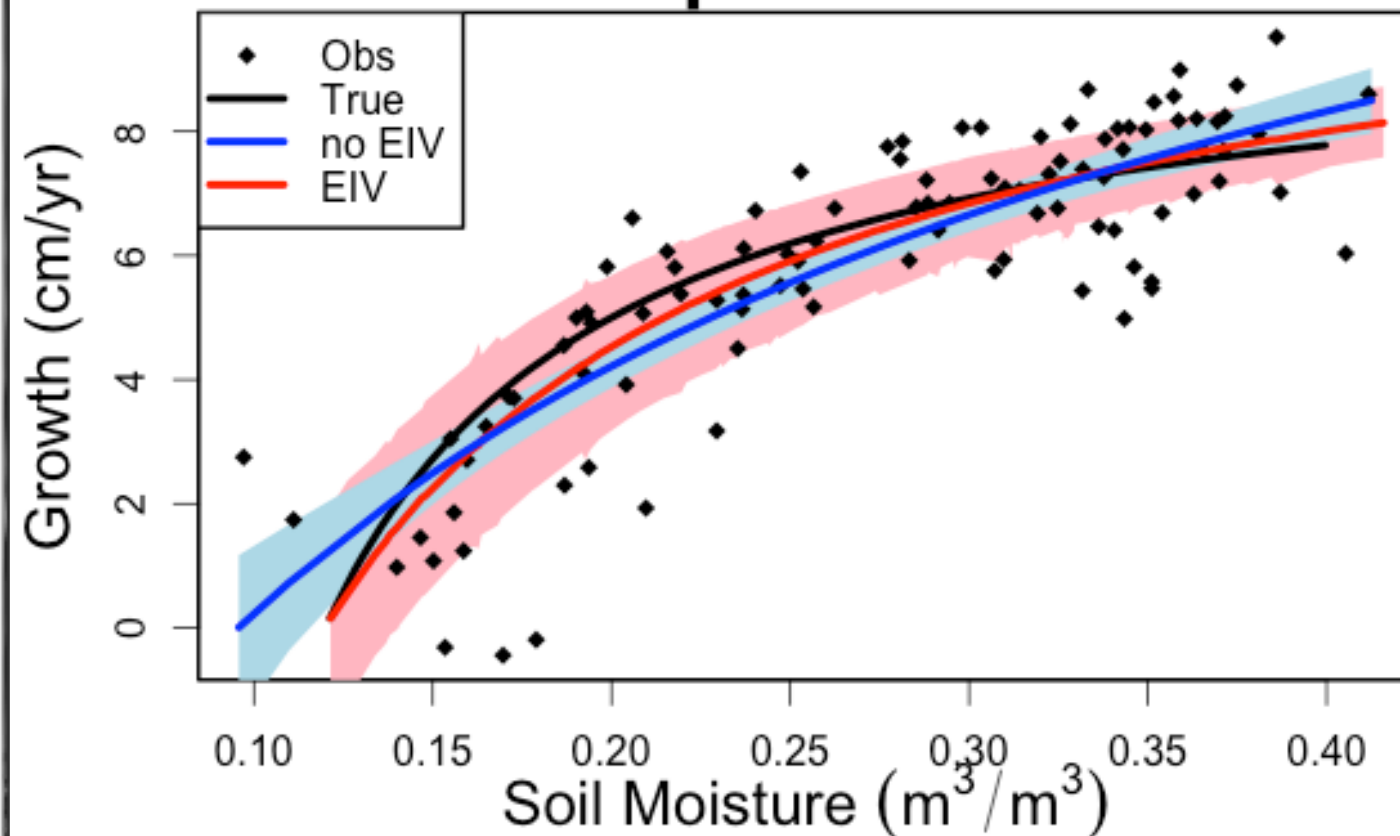
- Observed data can be a different type (proxy)
  - e.g. calibration curves
- Very useful to have informative priors



## Calibration



## Growth Response to Moisture

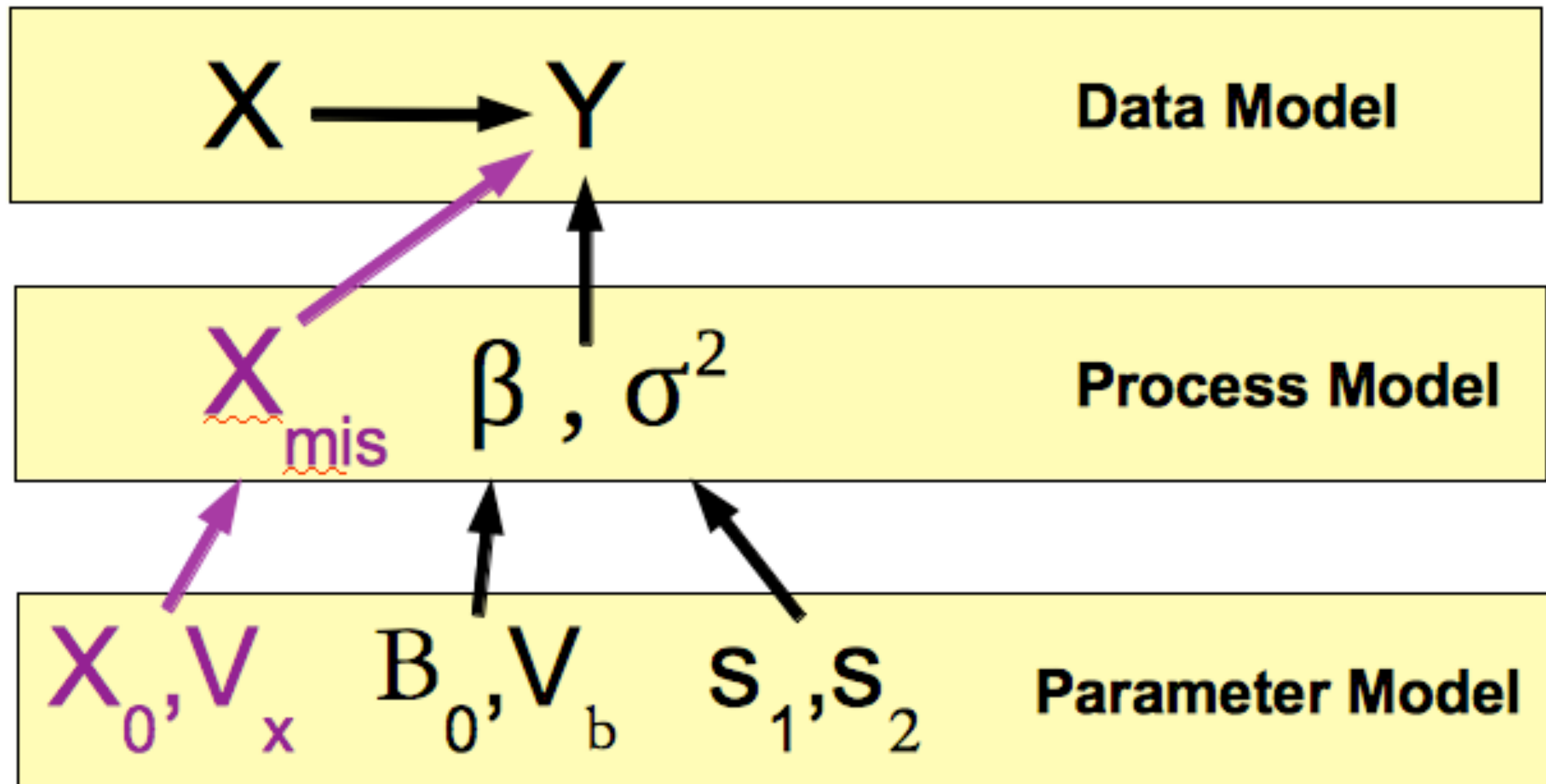


# Latent Variables

- Variables that are not directly observed
- Values are inferred from model
  - Parameter model: prior on value
  - Data and Process models provide constraint
- MCMC integrates over (by sampling) the values the unobserved variable could take on
- Contribute to uncertainty in parameters, model
- Ignoring this variability can lead to falsely overconfident conclusions



# MISSING DATA



Data needs to be **Missing At Random!!**

# JAGS example: Simple Regression

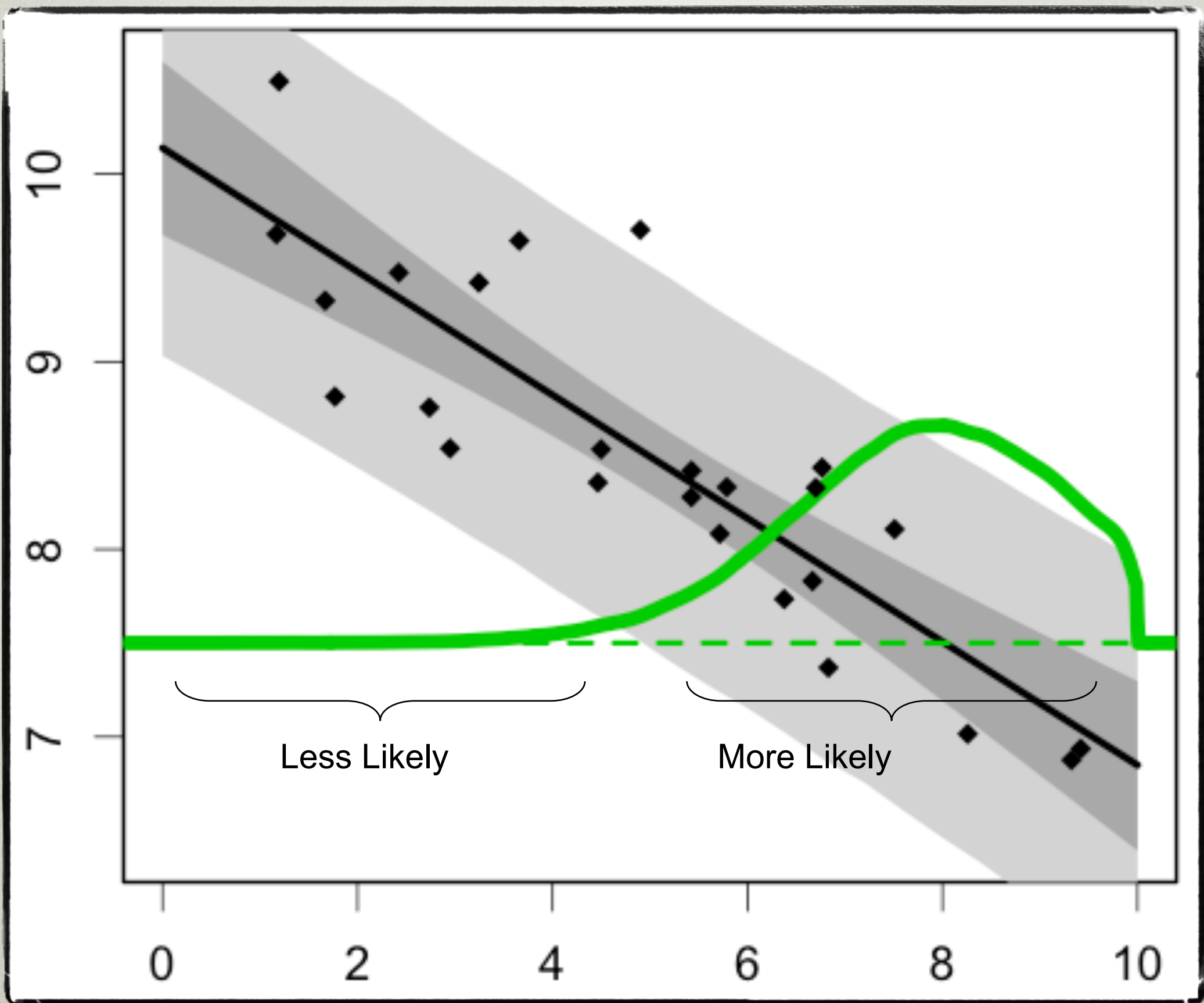
```
model{
  ## priors
  for(i in 1:2) { beta[i] ~ dnorm(0,0.001)}
  sigma ~ dgamma(0.1,0.1)
  for(i in mis) { x[i] ~ dunif(0,10)}

  for(i in 1:n){
    mu[i] <- beta[1]+beta[2]*x[i]
    y[i] ~ dnorm(mu[i],sigma)
  }
}
```

Vector giving indices of  
missing values

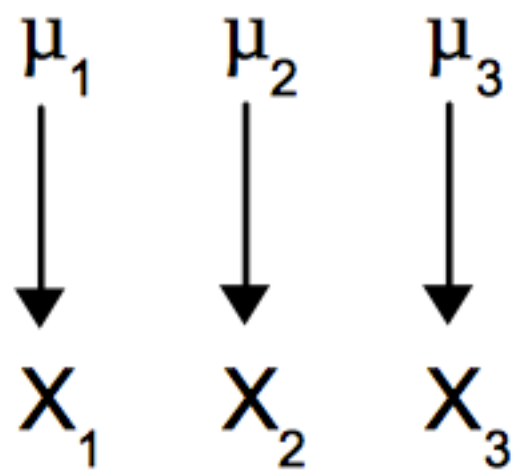
X	Y
4.68	8.46
2.95	8.55
9.09	7.01
8.15	9.06
1.76	11.38
4.23	9.12
7.73	7.3
2.43	8.02
6.46	8.45
4.06	8.95
2.42	9.62
0.6	9.15
8.17	7.51
0.22	10.8
4.93	9.78
2.99	10.71
8.36	8.89
6.4	8.21
8.17	6.22
6.46	5.4
1.82	10.05
9.52	7.96
2.44	9.63
6.84	7.05
7.42	8.73
mis = 26	NA 7.5



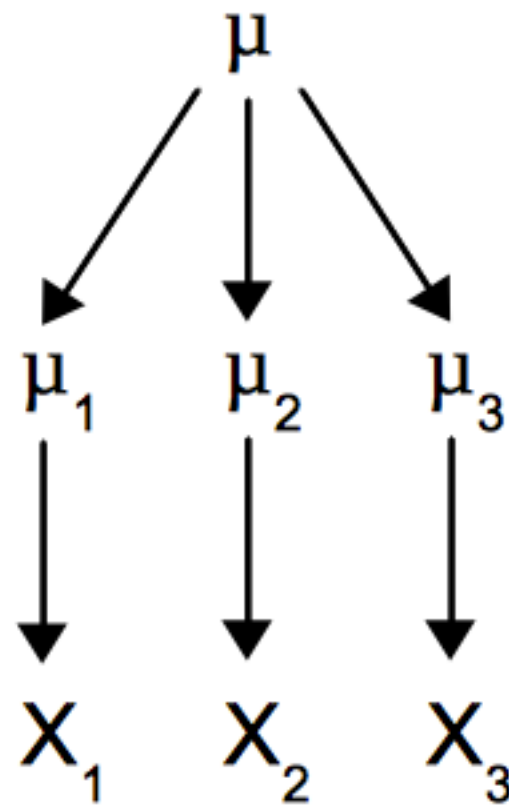


# HIERARCHICAL MODELS

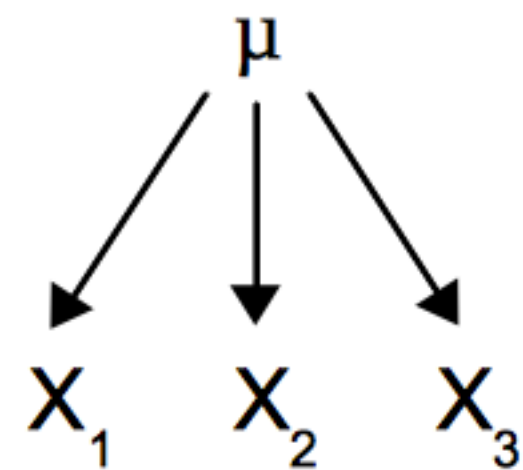
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Independent



Hierarchical



Shared



**Data Model**

$Y_1 \dots Y_k \dots Y_n$

**Process Model**

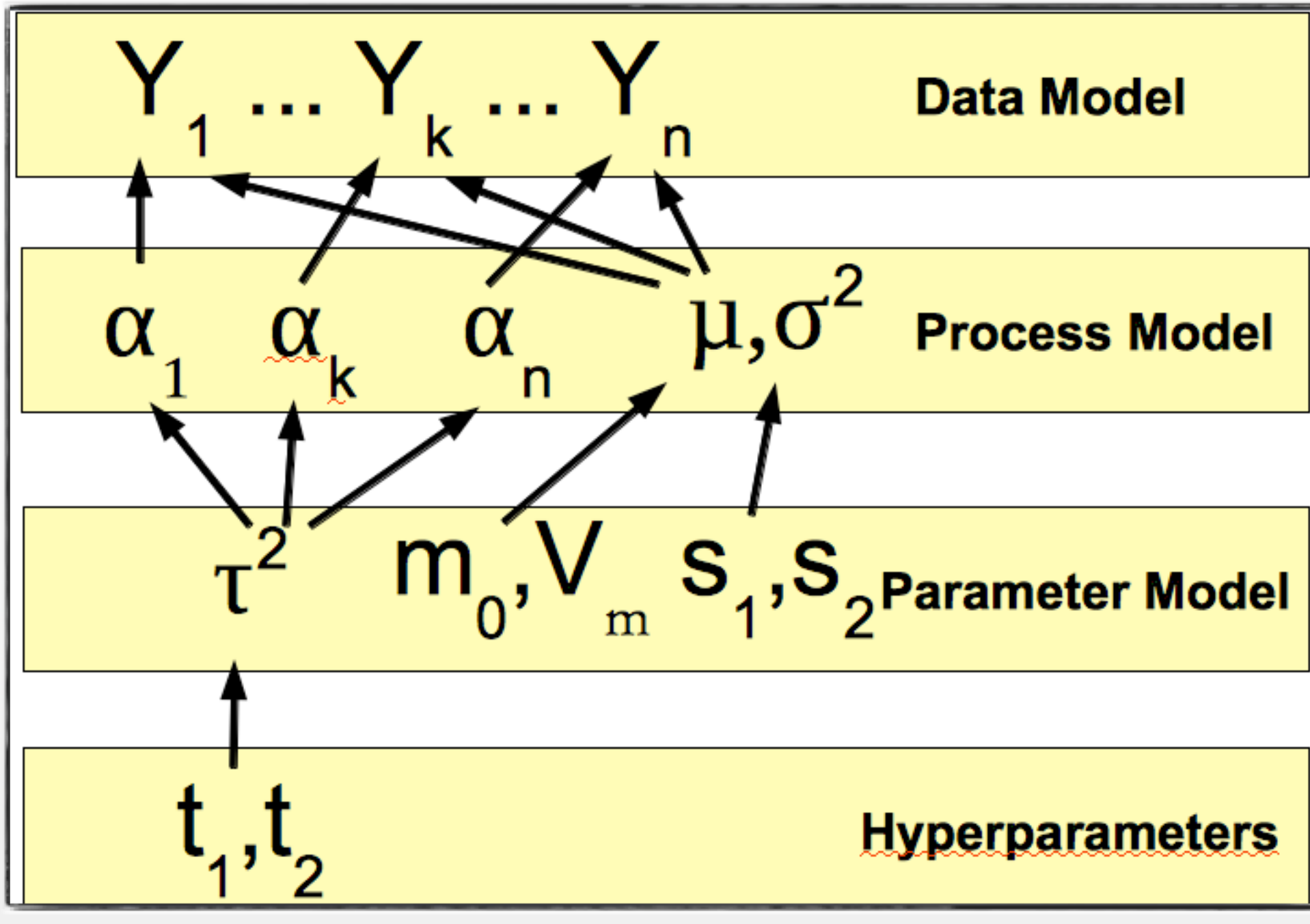
$\mu_1 \mu_k \mu_n \sigma^2$

**Parameter Model**

$\mu, \tau^2 S_1, S_2$

**Hyperparameters**

$m_0, V_m t_1, t_2$

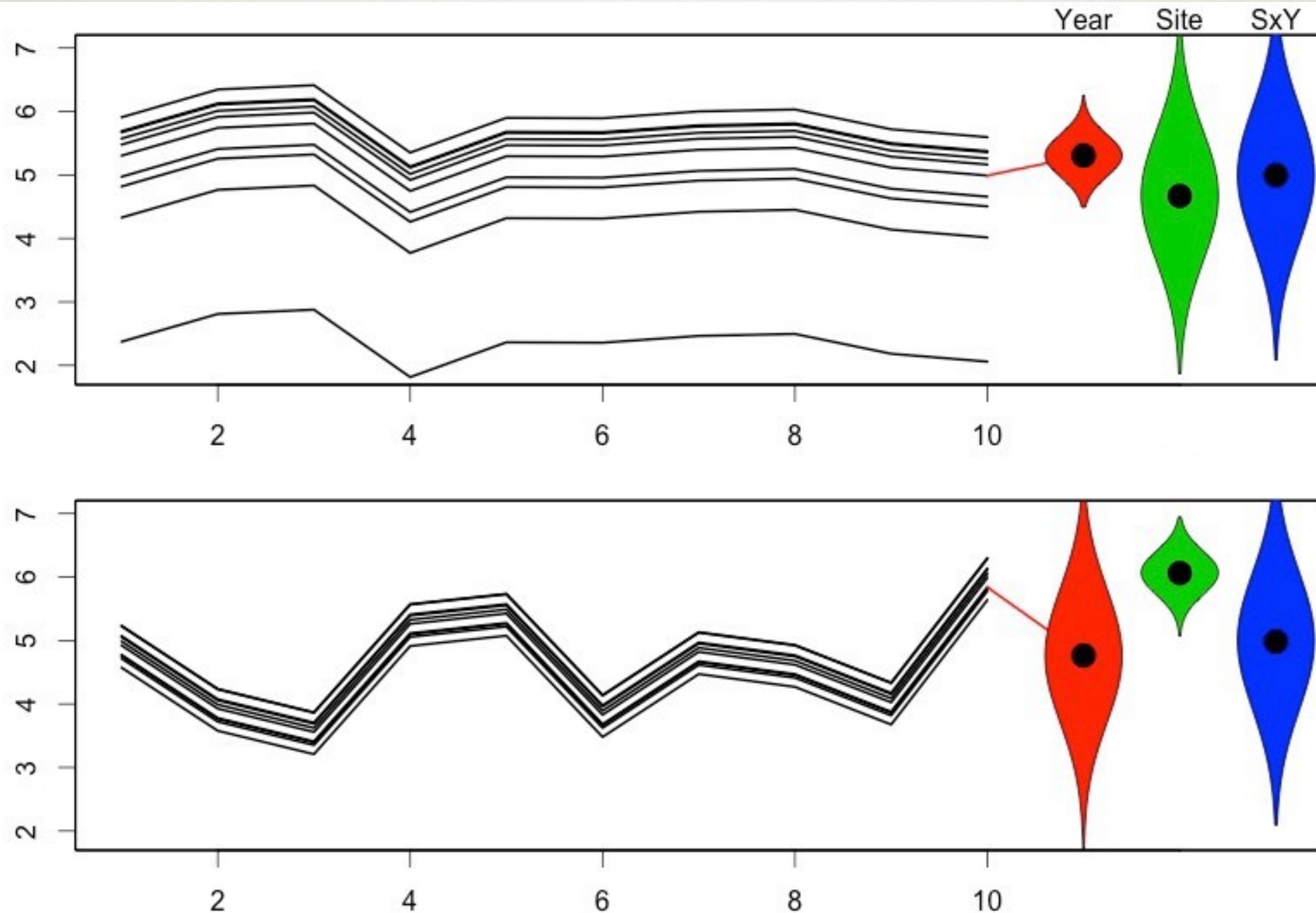


$$Y_k \sim N(\mu_g + \alpha_k, \sigma^2)$$

$$\alpha_k \sim N(0, \tau^2)$$



# IMPACTS ON INFERENCE





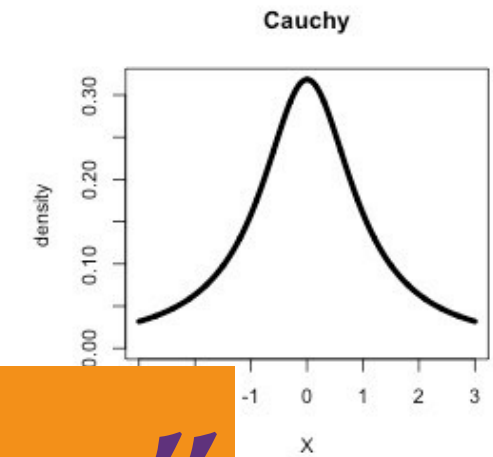
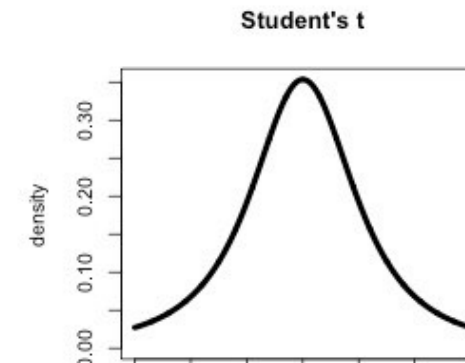
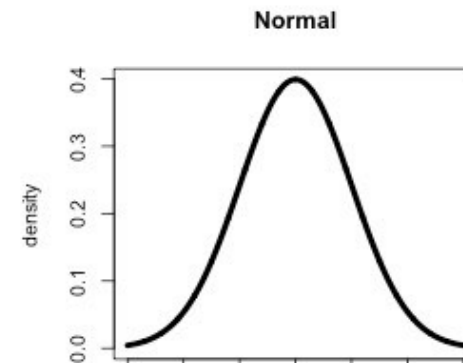
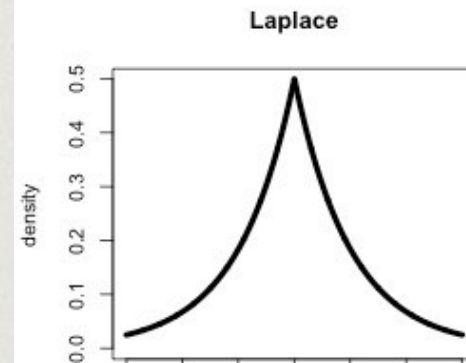
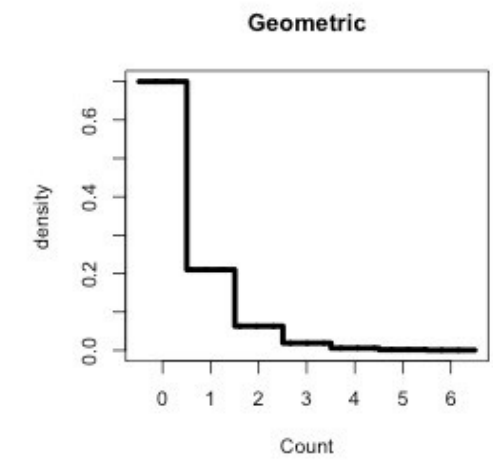
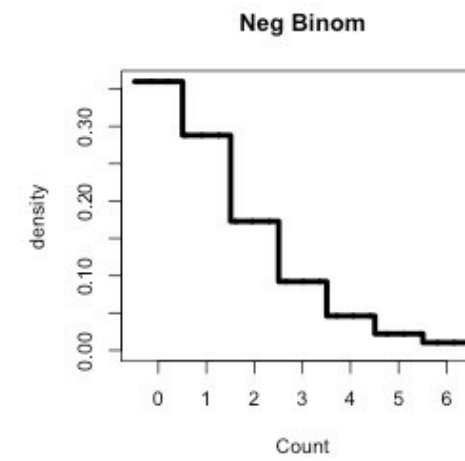
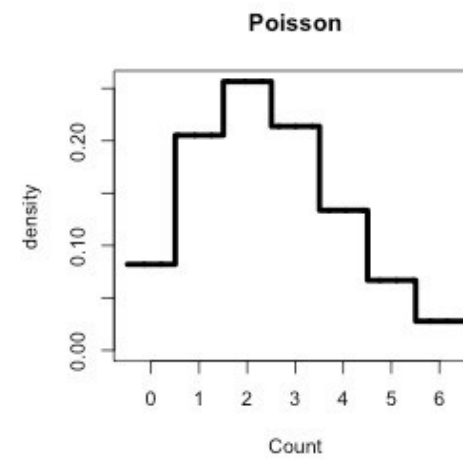
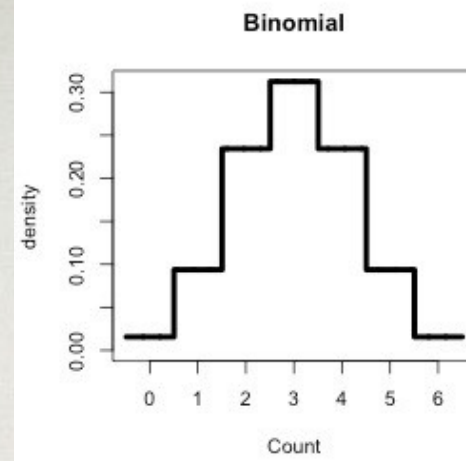
# EXPLAINING UNEXPLAINED VARIANCE

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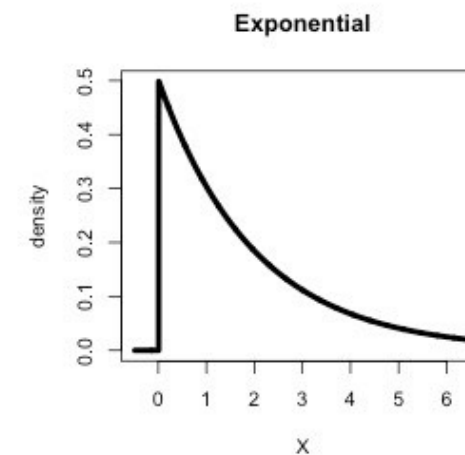
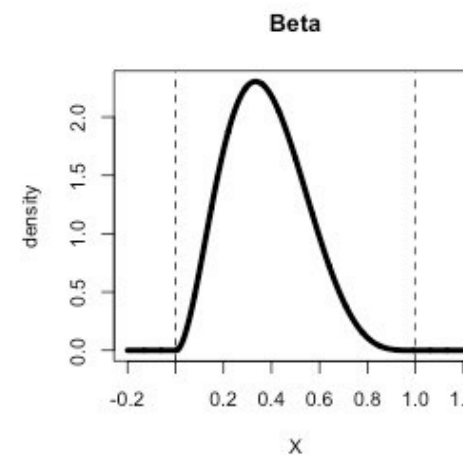
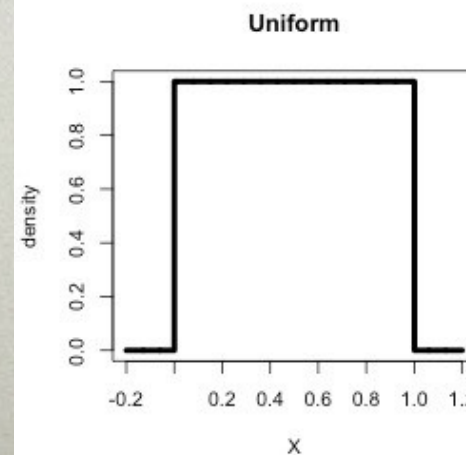
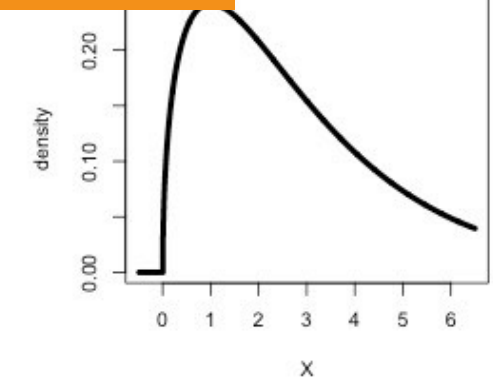
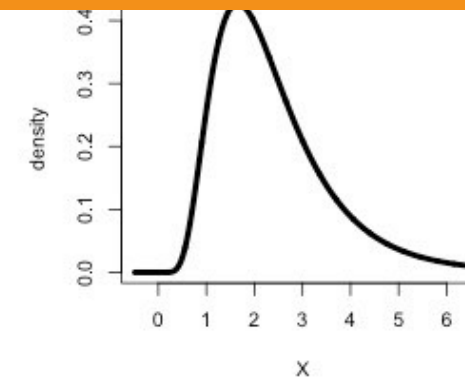
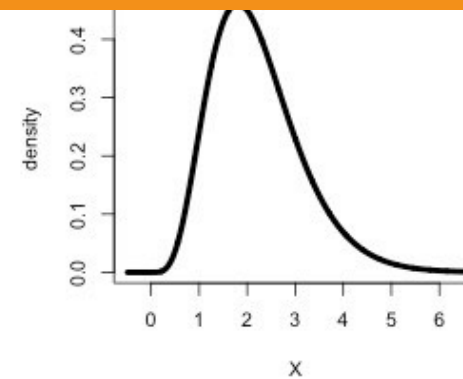
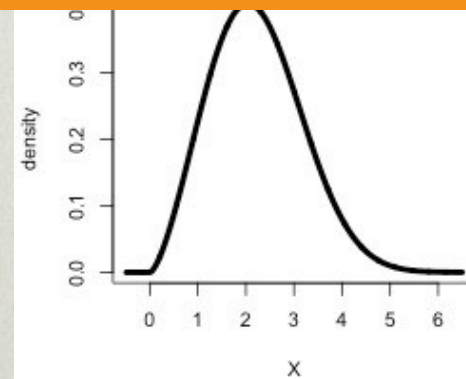
- Random effects attempt to account for the unexplained variance associated with some group (plot, year, etc.) due to all the things that were not measured
- May point to scales that need additional explanation
- Adding covariates may explain some portion of this variance, but there's always something you didn't measure
- Sometimes additional fixed effects not justified (model selection)



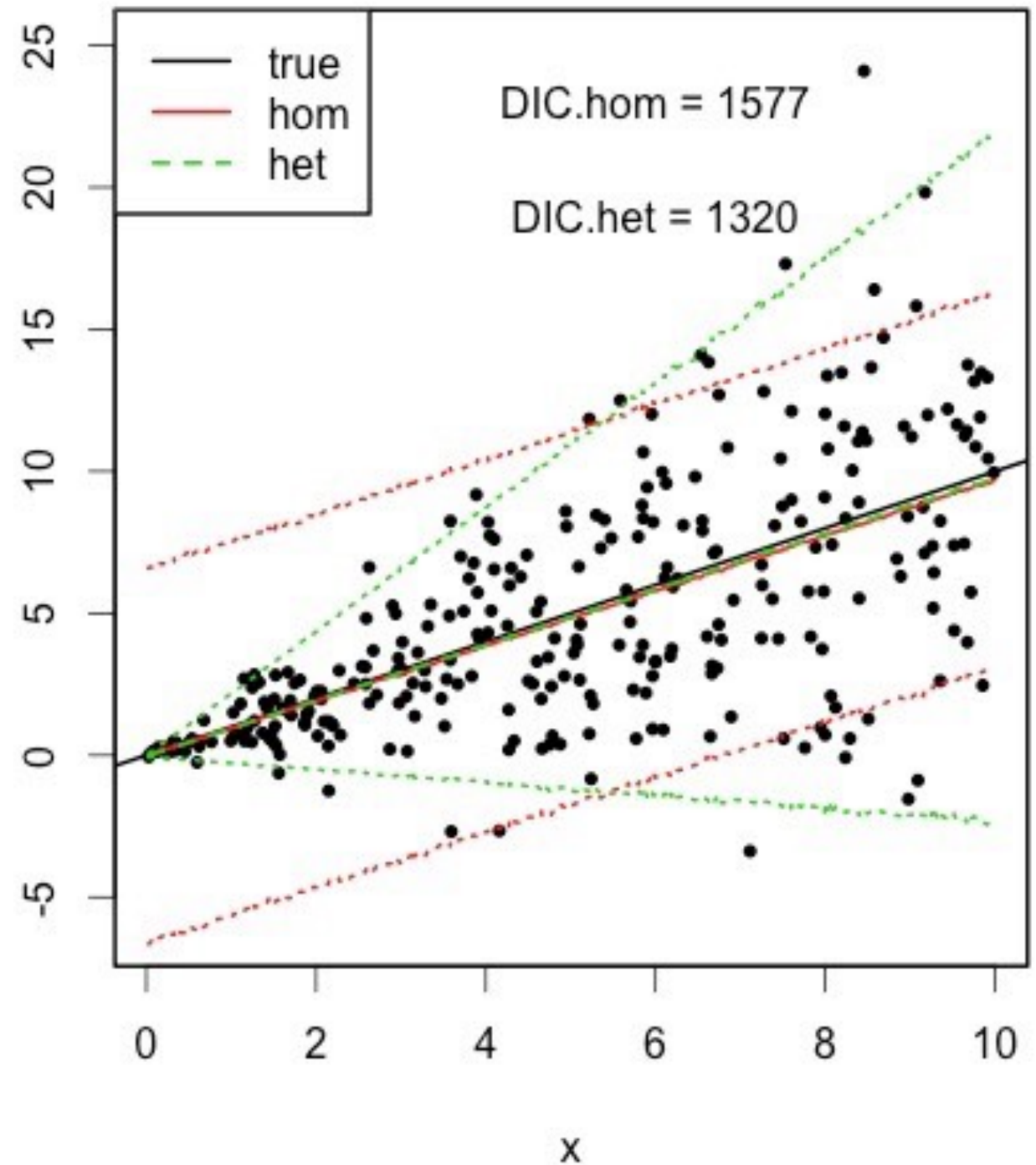
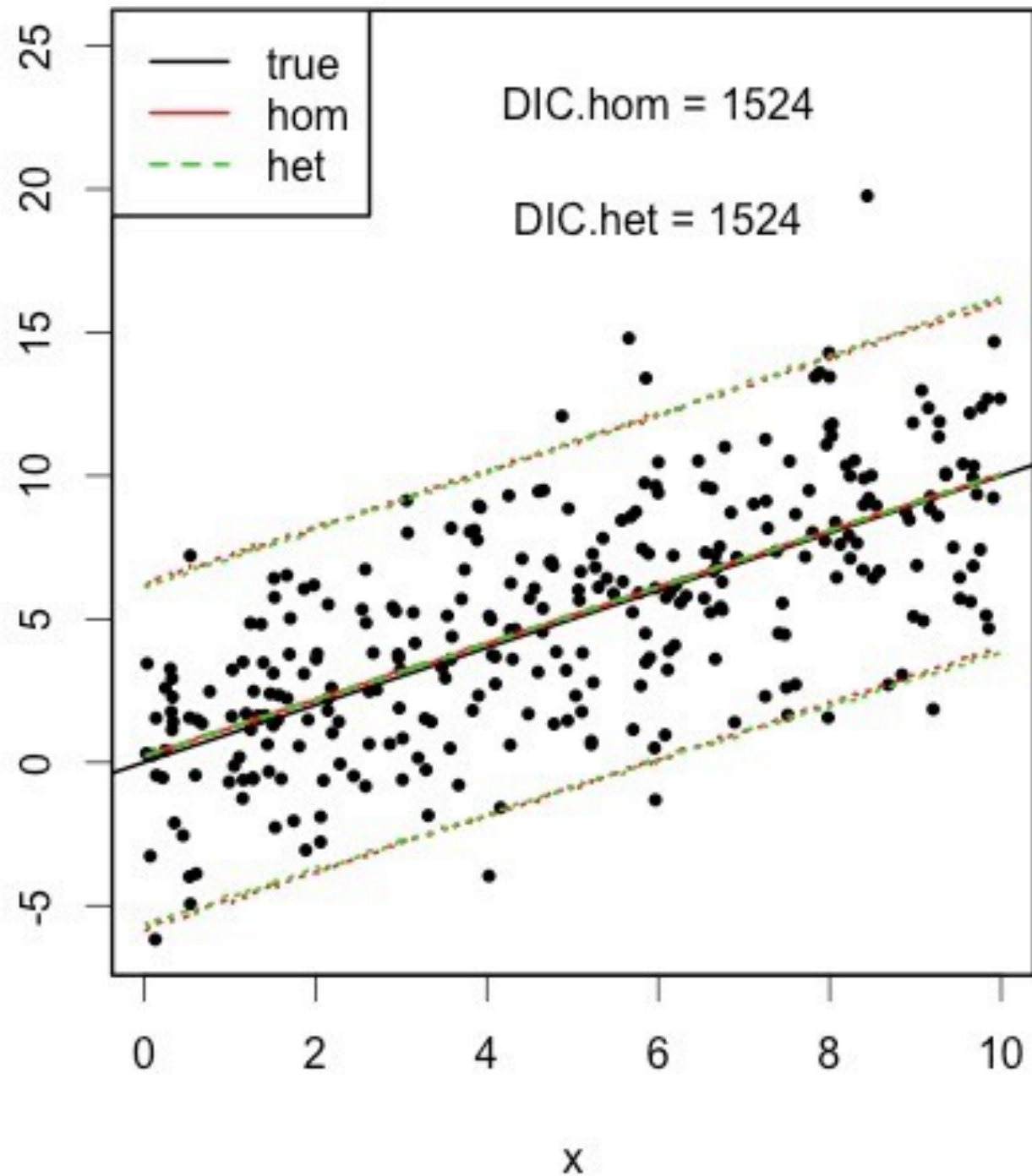
# Choosing a Distribution



**Resist the “Gaussian Reflex”**



# HETEROSKEDASTICITY





$$y \sim N(\beta_1 + \beta_2 x, (\alpha_1 + \alpha_2 x)^2)$$

$X \longrightarrow Y$

**Data Model**

$\beta, \alpha$

**Process Model**

$B_0, V_b$

$A_0, V_a$

**Parameter Model**

# Example: Linear varying SD

```
model{
  for(i in 1:2) { beta[i] ~ dnorm(0,0.001)} ## priors
  prec ~ gamma(s1,s2)
  for(i in 1:n){
    mu[i] <- beta[1]+beta[2]*x[i]
    y[i] ~ dnorm(mu[i],prec)
  }
}
```



```
model{
  for(i in 1:2) { beta[i] ~ dnorm(0,0.001)} ## priors
  for(i in 1:2) { alpha[i] ~ dlnorm(0,0.001)} ## was prec ~ gamma(a1,a2)
  for(i in 1:n){
    prec[i] <- 1/pow(alpha[1] + alpha[2]*x[i],2)
    mu[i] <- beta[1]+beta[2]*x[i]
    y[i] ~ dnorm(mu[i],prec[i])
  }
}
```